

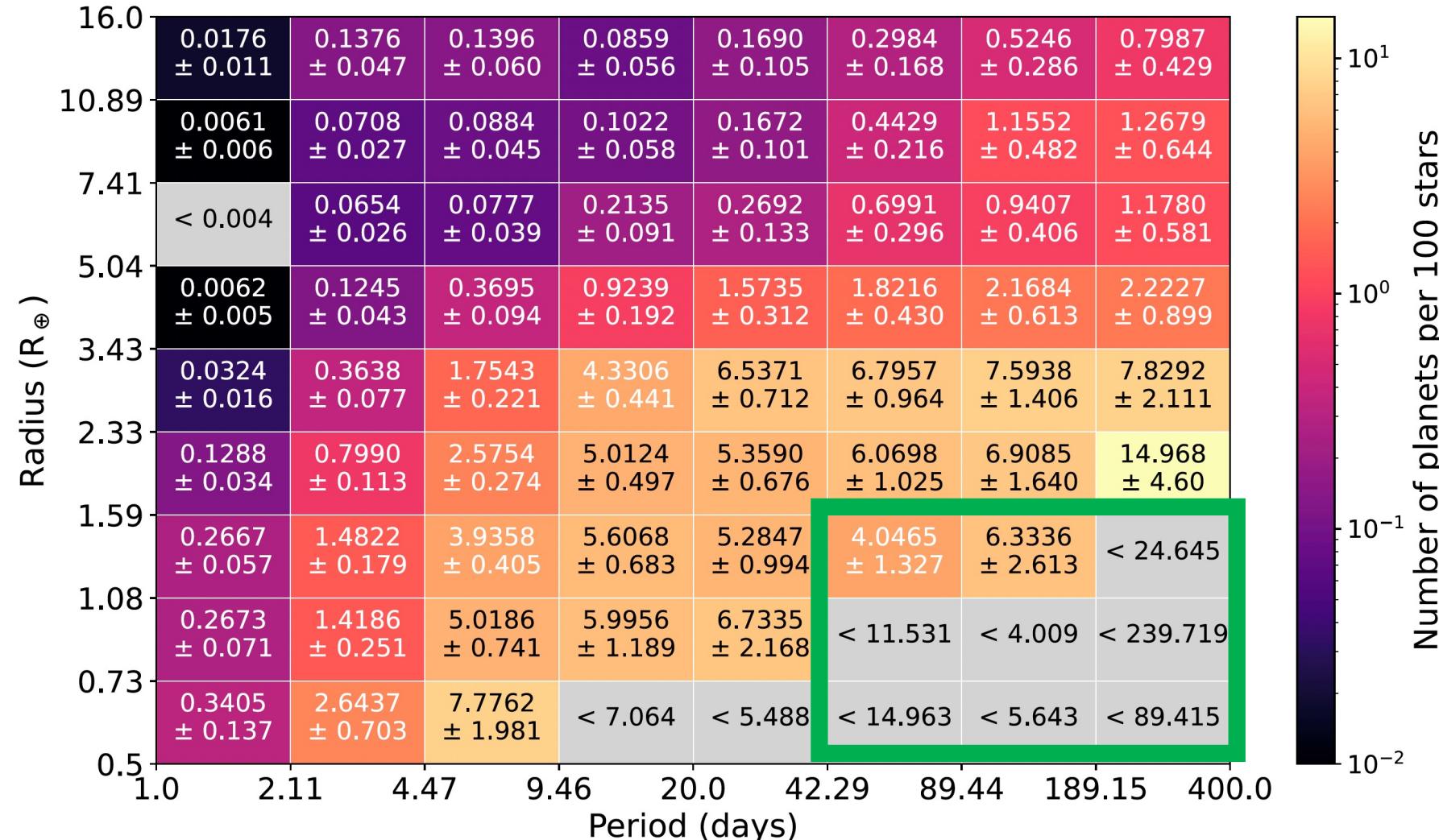
Reliable detection of small long-period planets in Kepler data

Oryna Ivashtenko, Barak Zackay
Weizmann Institute of Science

Current exoplanet population from *Kepler*

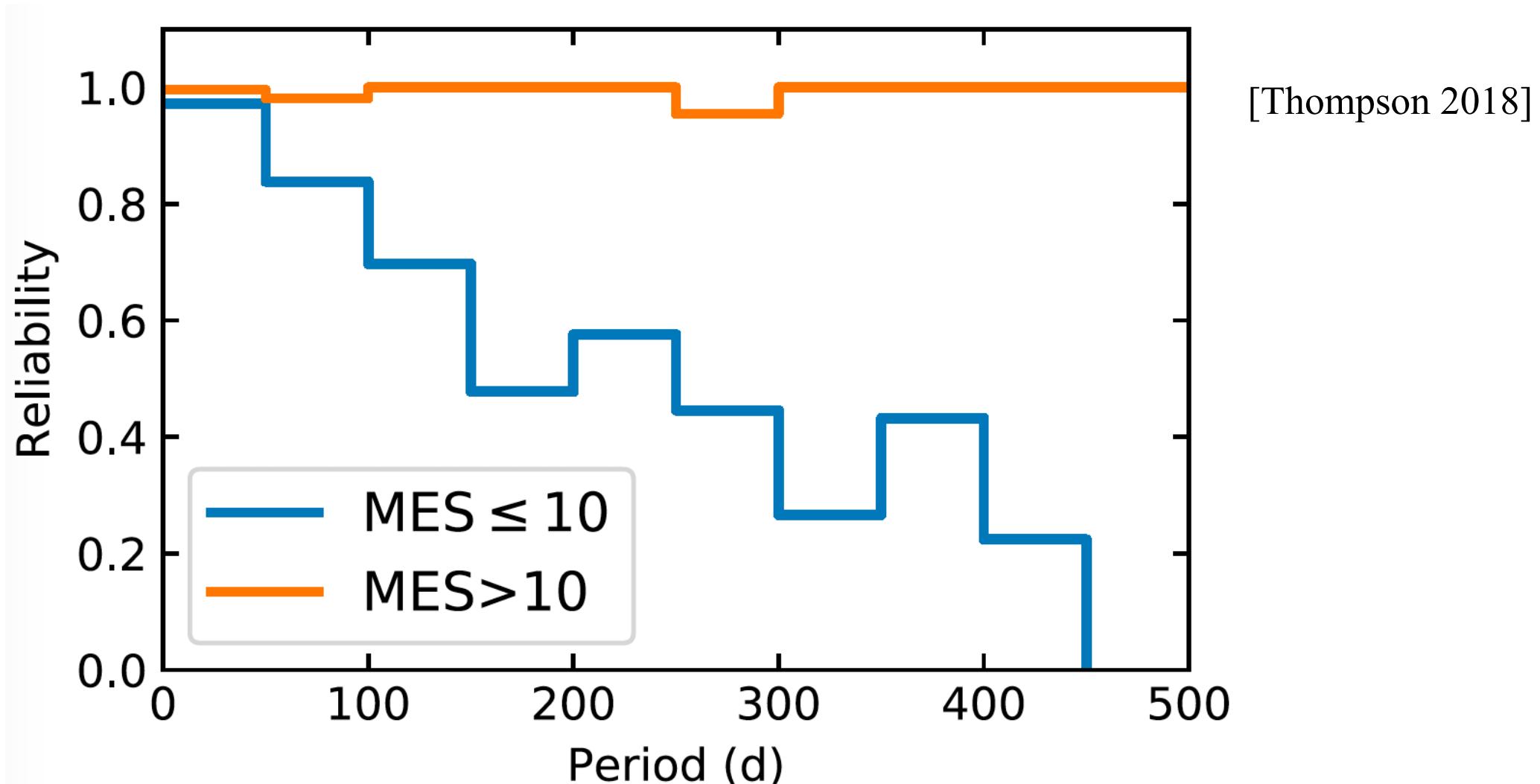
Kepler Exoplanetary occurrence rates around FGK stars:

[Dattilo, Batalha, Bryson 2023]



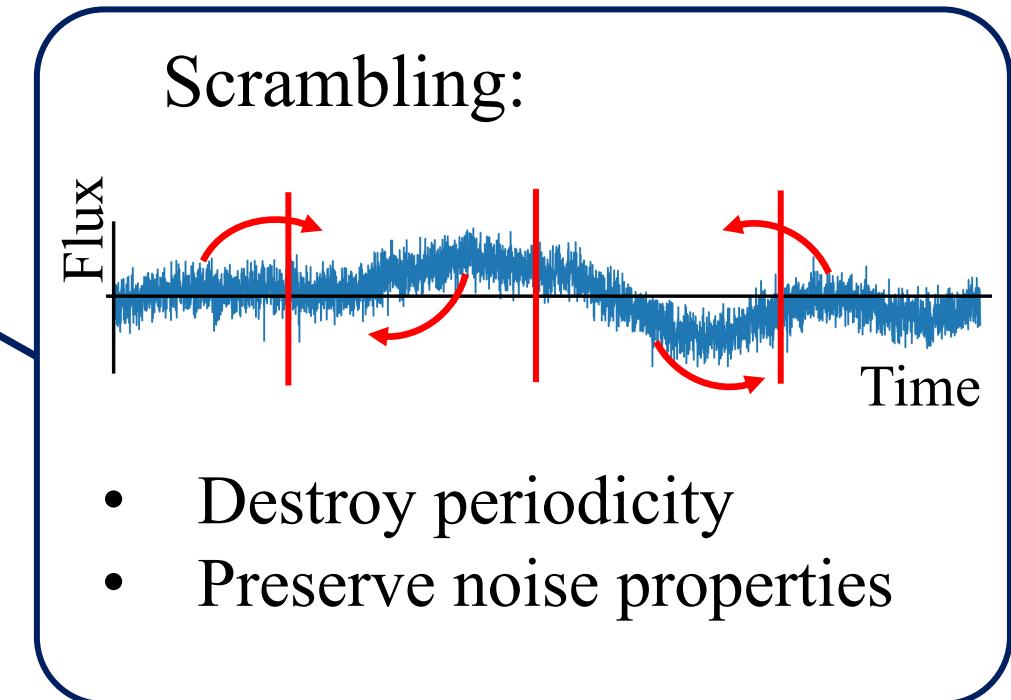
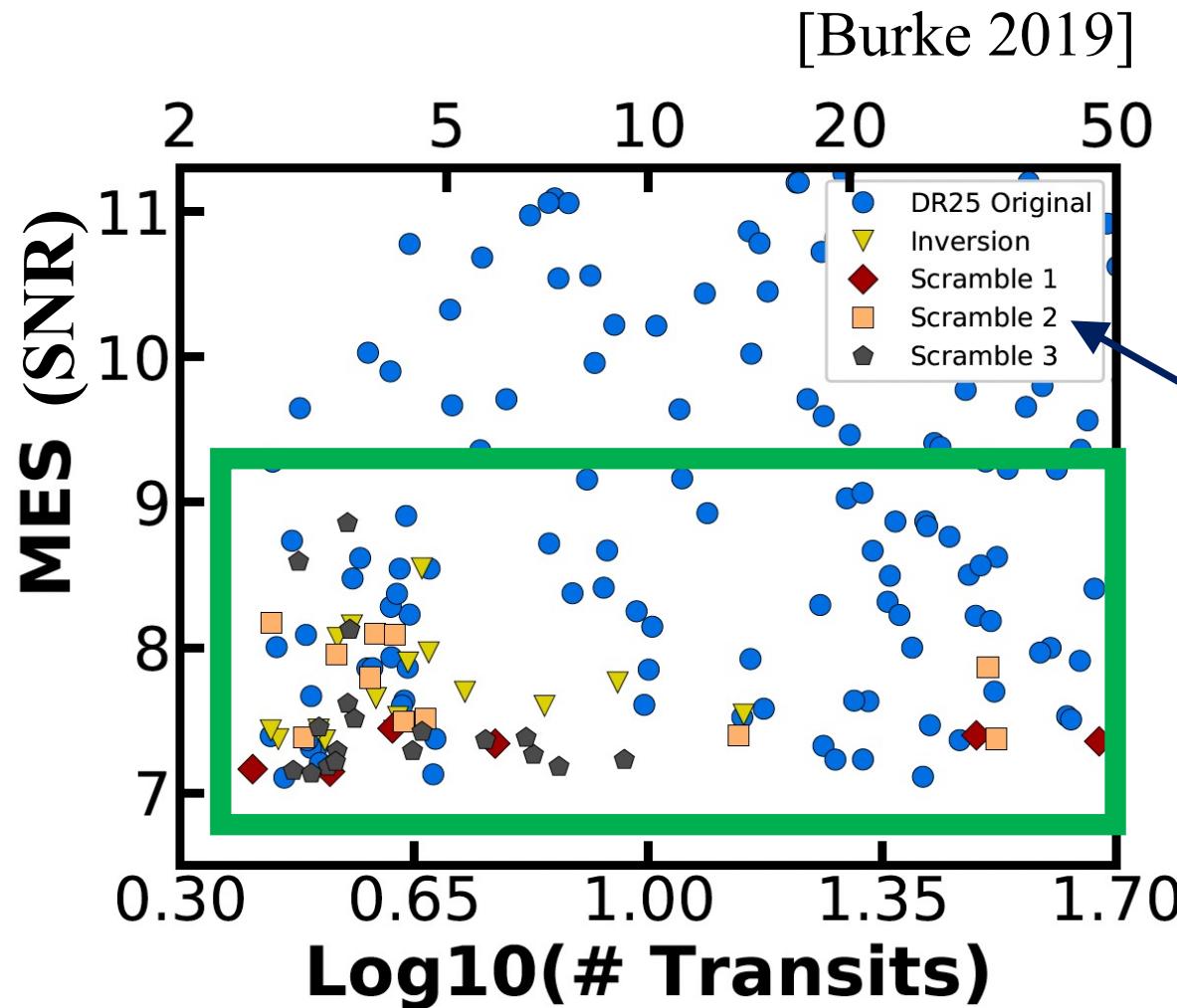
Reliability challenge of *Kepler* Catalog

- **Reliability:** Fraction of catalog events that are real planets



Challenge: false alarms at low MES, long period

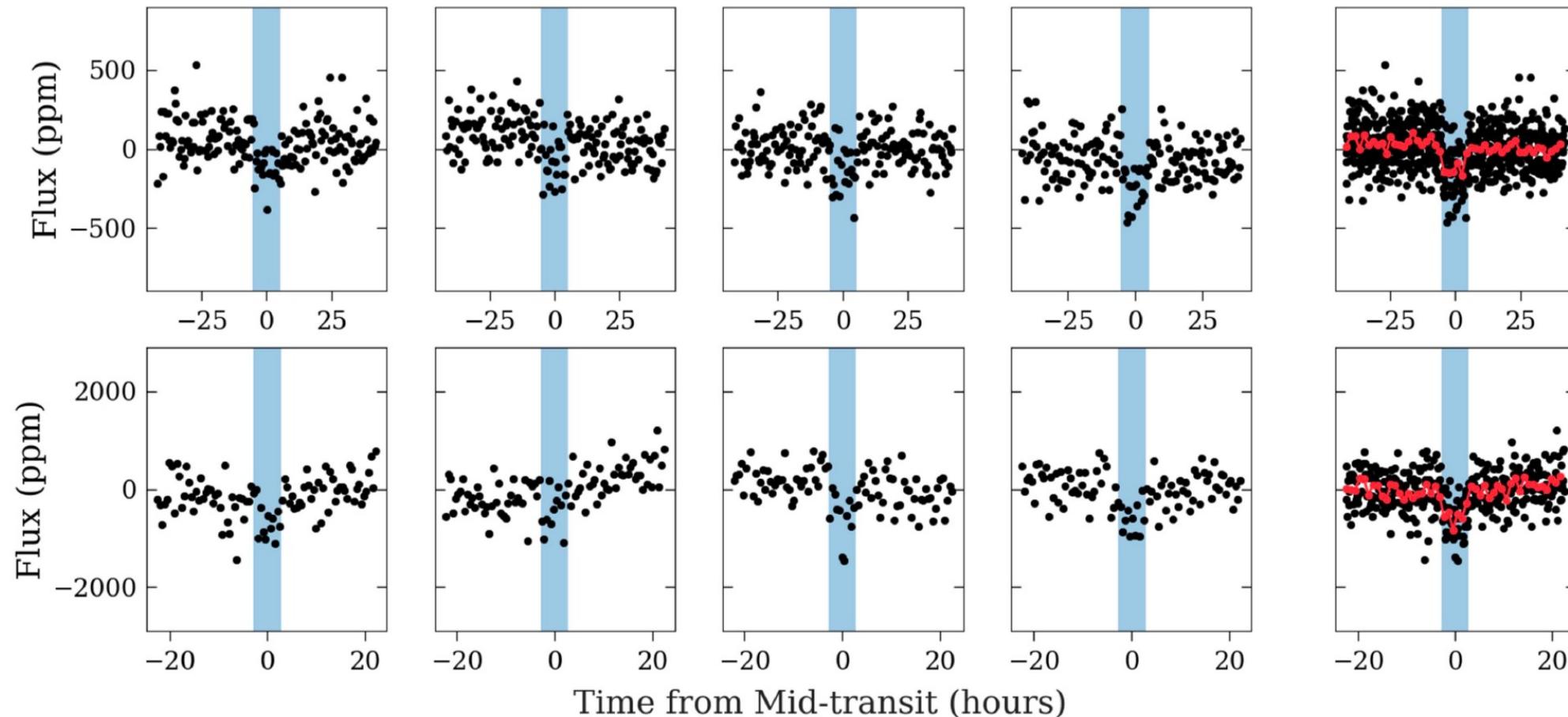
- MES: Multiple-event statistic (SNR of multiple-transit signal)



False Alarms

[Source: Mullaly 2018]

Example of how a false alarm in inverted light curve can mimic a confirmed planet (the reader was invited to guess which is which)



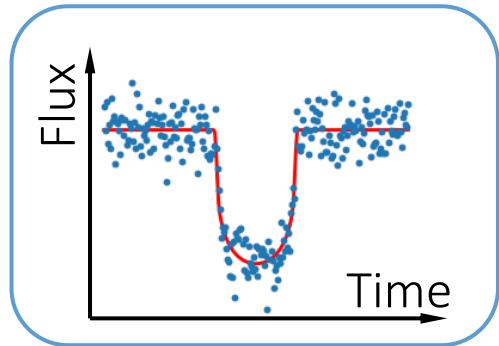
Our Independent search pipeline

- **Goal:** Estimate the population of small long-period planets with *Kepler*
- **Focus of the pipeline:** Search reliability (control false alarms)
- **Main methods:**
 - + Exact detection statistic
 - + Background distribution control
 - + Empirical significance estimation

Pipeline methods

Single-transit detection statistic

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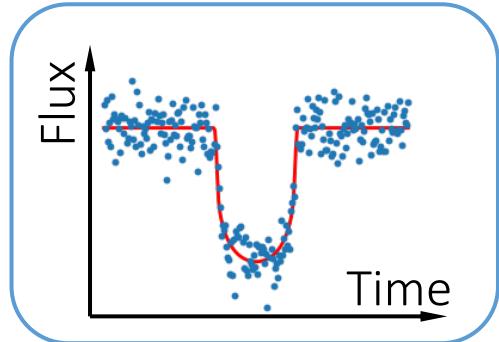


Data model:

$$\vec{d} = A\vec{h} + \mathcal{N}(0, \mathbf{C})$$

Flux Template Covariance matrix

Single-transit detection statistic



Data model:

$$\vec{d} = A\vec{h} + \mathcal{N}(0, \mathbf{C})$$

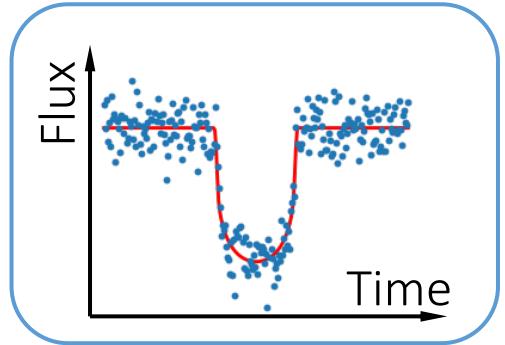
Flux Template Covariance matrix



Optimal detection test:

$$\rho_{\text{SES}} = \vec{h}^T \mathbf{C}^{-1} \vec{d} \qquad \Leftarrow \qquad \log \frac{\mathcal{L}(\vec{d} | \mathcal{H}_{\text{planet}})}{\mathcal{L}(\vec{d} | \mathcal{H}_{\text{noise}})}$$

Calculating Single-event statistic



$$\rho_{\text{SES}} = \vec{h}^T \mathbf{C}^{-1} \vec{d}$$

Template
(use template bank)

Inverse covariance matrix

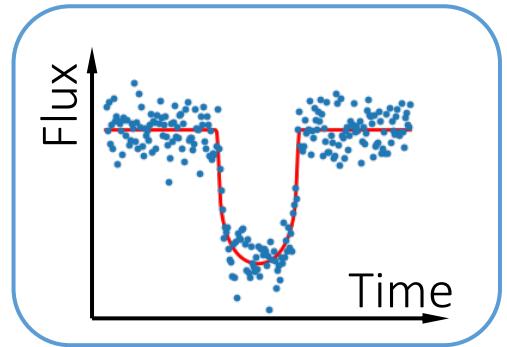
Data

```
graph TD; SES["ρSES = h̄^T C⁻¹ d̄"] --- Template["Template  
(use template bank)"]; SES --- Inverse["Inverse covariance matrix"]; SES --- Data["Data"];
```

The diagram illustrates the formula for calculating the Single-Event Statistic (ρ_{SES}). The formula is $\rho_{\text{SES}} = \vec{h}^T \mathbf{C}^{-1} \vec{d}$. The components of the formula are represented by circles: \vec{h}^T , \mathbf{C}^{-1} , and \vec{d} . Arrows point from three boxes below the formula to these circles: "Template (use template bank)" points to \vec{h}^T , "Inverse covariance matrix" points to \mathbf{C}^{-1} , and "Data" points to \vec{d} .

Calculating Single-event statistic

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Time domain

$$\rho_{\text{SES}} = \hat{h}^T \mathbf{C}^{-1} \hat{d}$$

Template
(use template bank)

Inverse covariance matrix

Fourier domain

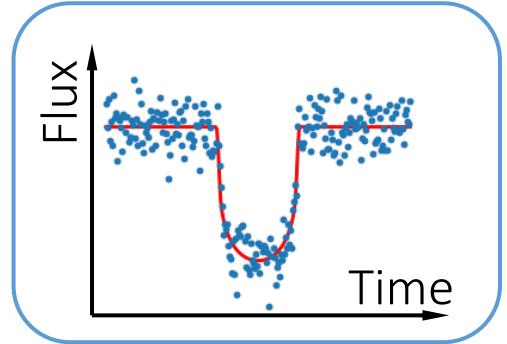
$$= \sum_f \frac{\hat{h}^\dagger(f) \hat{d}(f)}{\text{PSD}(f)}$$

Data

Power spectral density
(Measure from the data)

Calculating Single-event statistic

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Time domain

$$\rho_{\text{SES}} = \hat{h}^T \mathbf{C}^{-1} \hat{d}$$

Template
(use template bank)

Inverse covariance matrix

Fourier domain

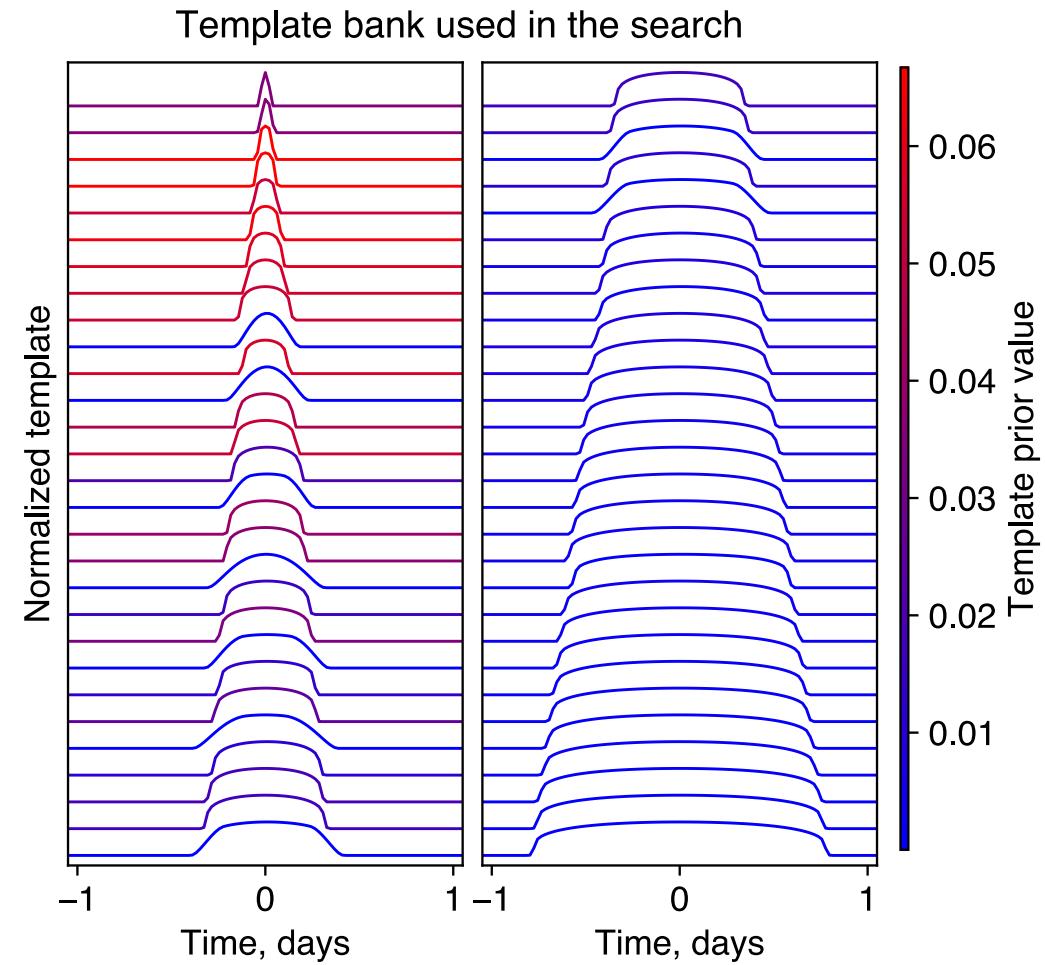
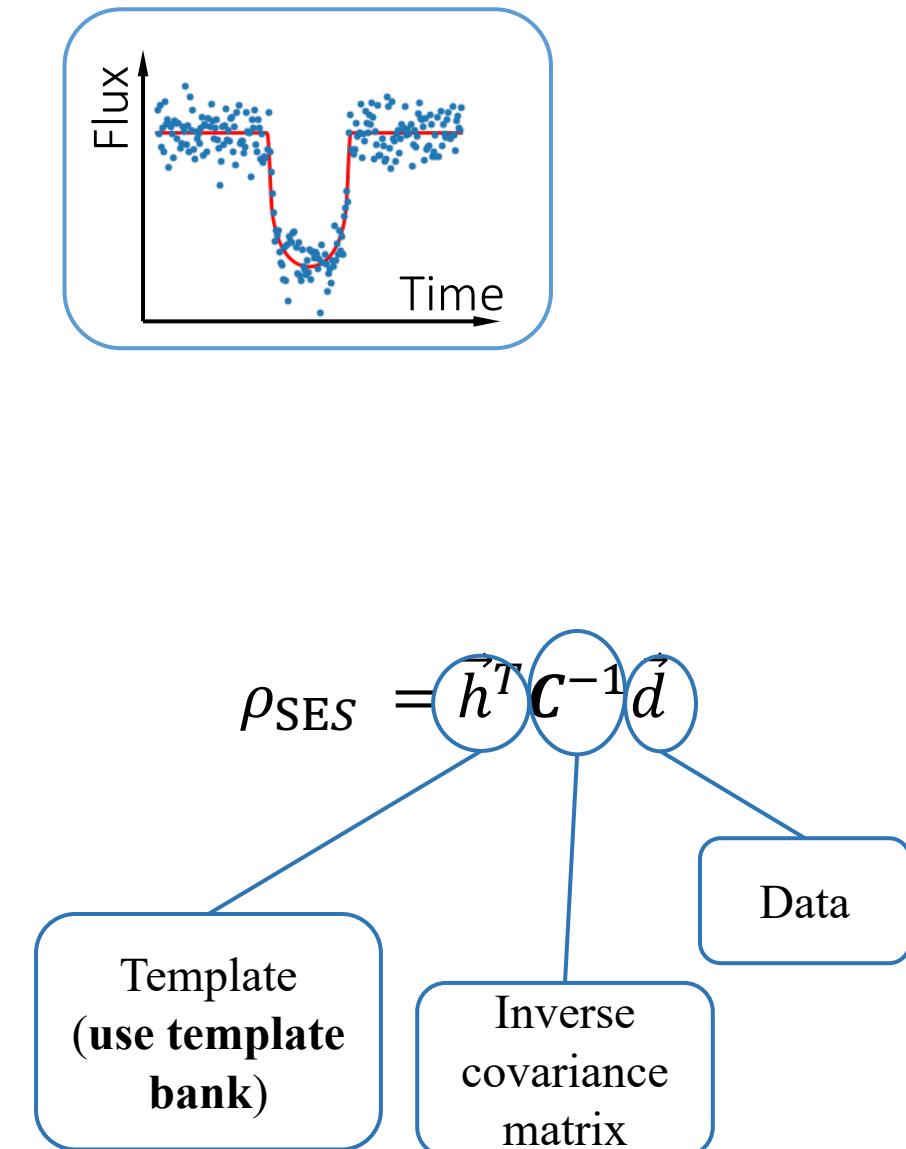
$$= \sum_f \frac{\hat{h}^\dagger(f) \hat{d}(f)}{\text{PSD}(f)}$$

Data

Power spectral density
(Measure from the data)

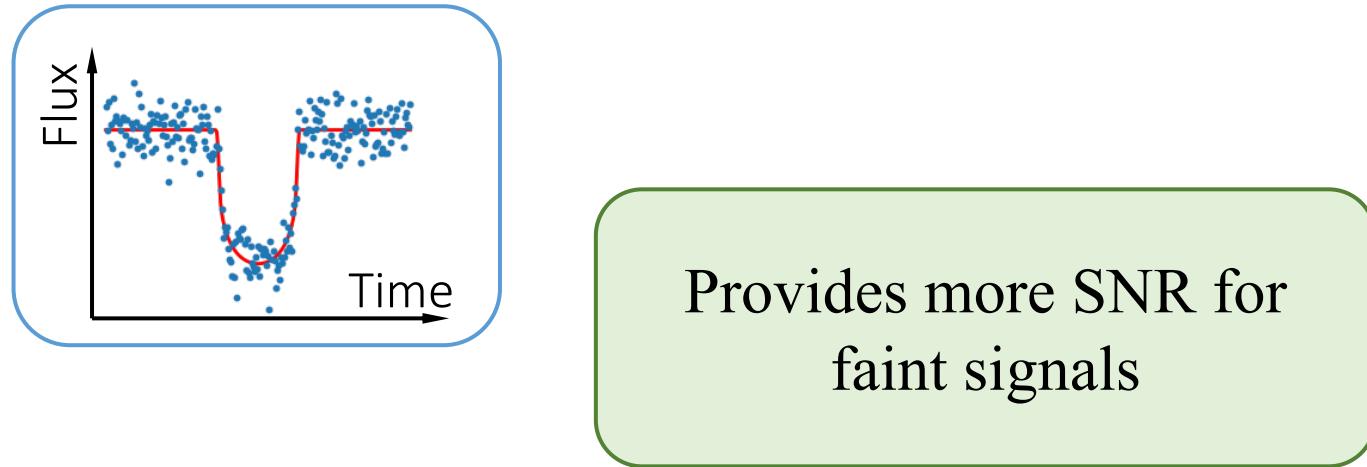
Efficiently treats stellar variability noise

Calculating Single-event statistic



Calculating Single-event statistic

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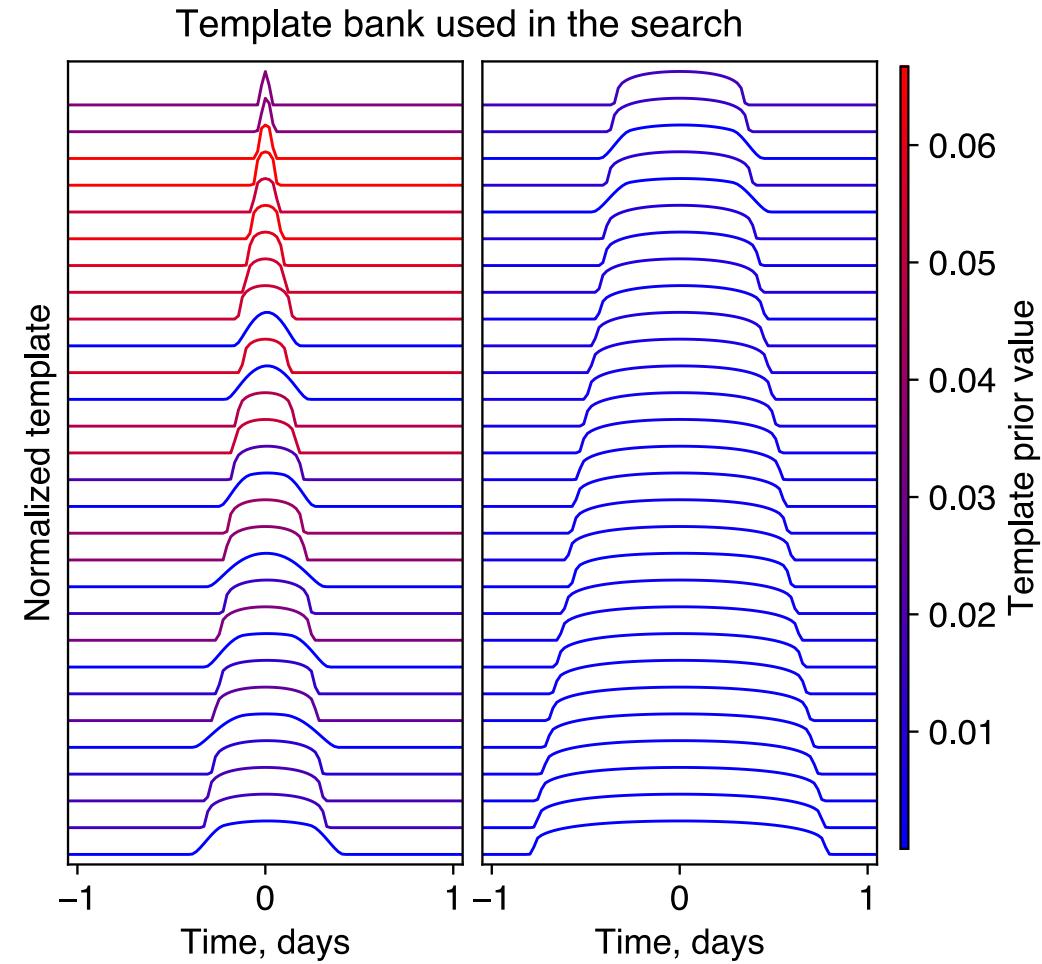


$$\rho_{\text{SES}} = \vec{h}^T \mathbf{C}^{-1} \vec{d}$$

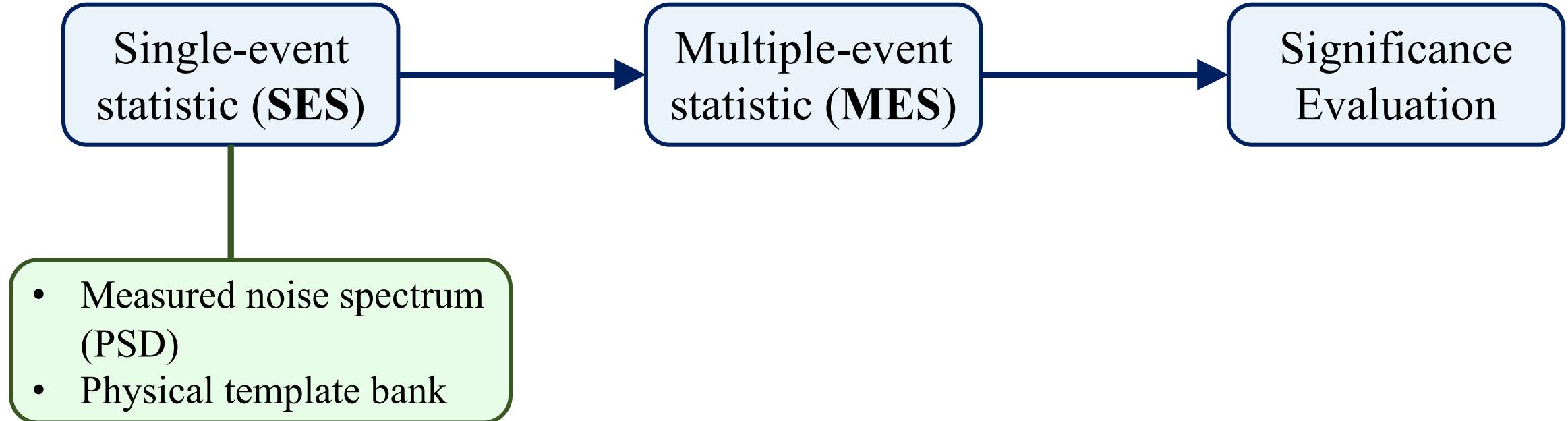
Template (use template bank)

Inverse covariance matrix

Data

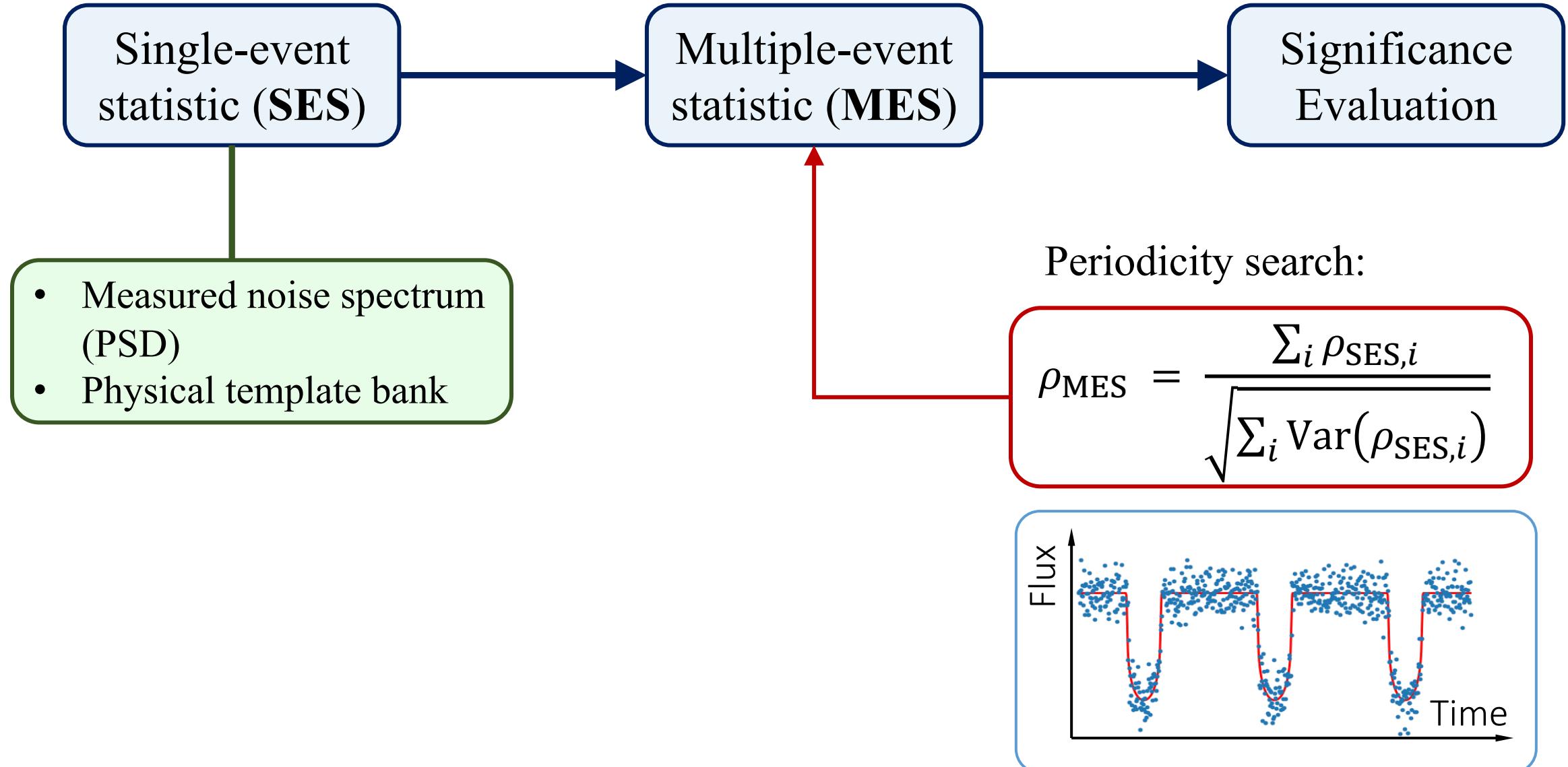


Search scheme



Search scheme

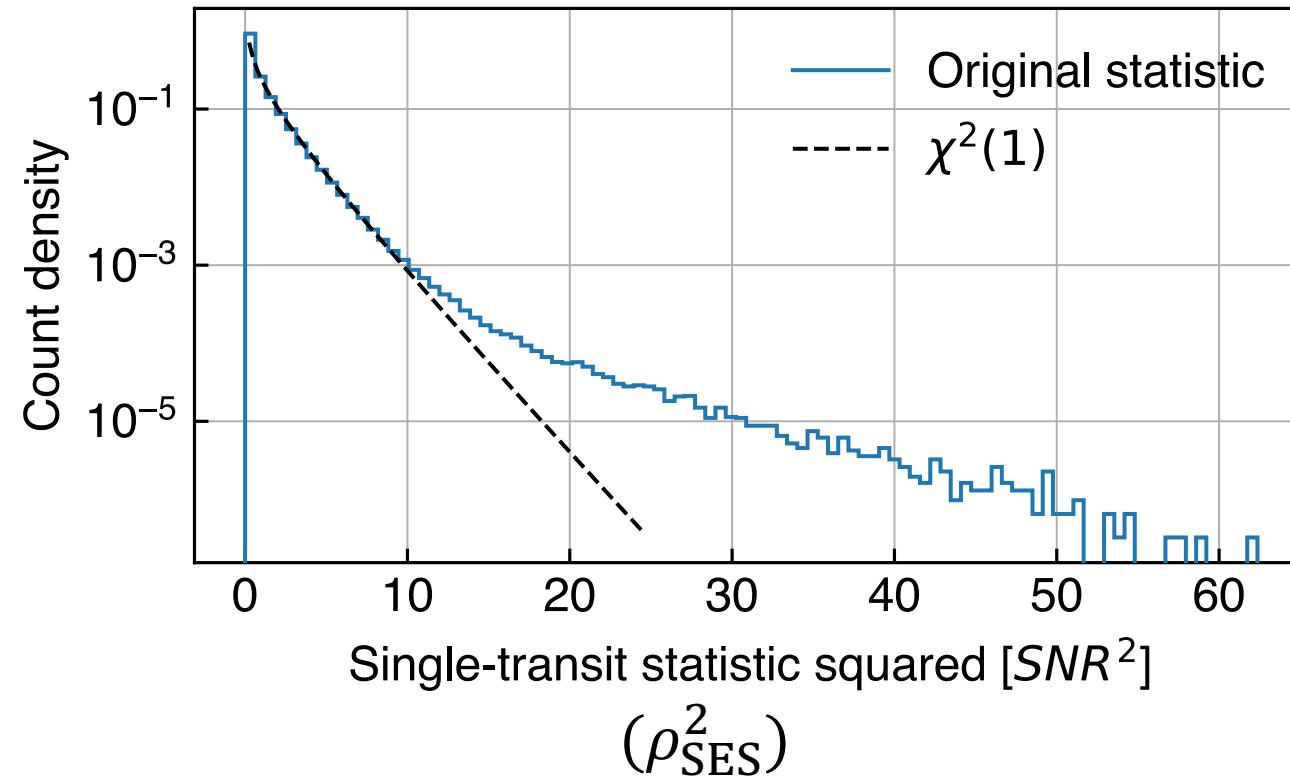
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Non-Gaussianity of single-event statistic (SES) distribution

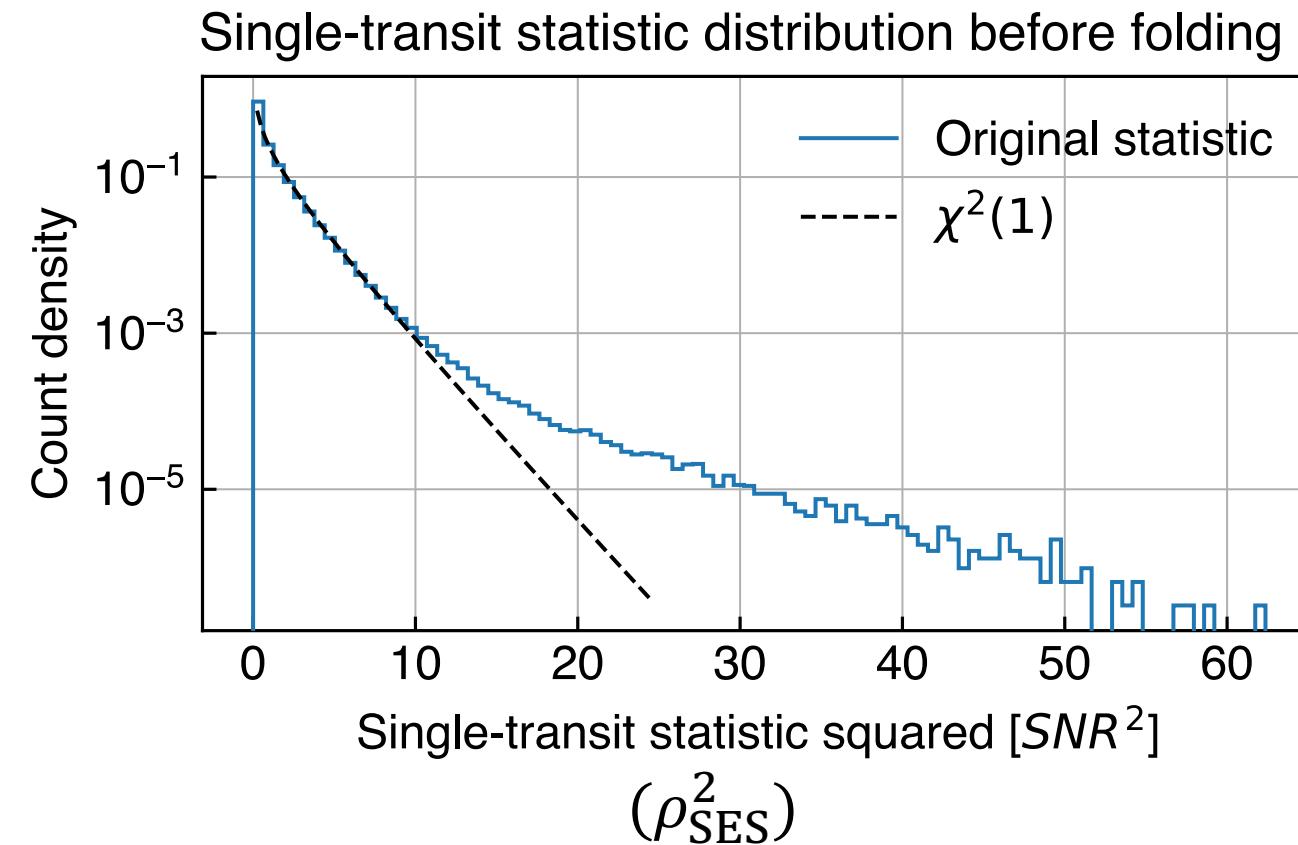
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Single-transit statistic distribution before folding

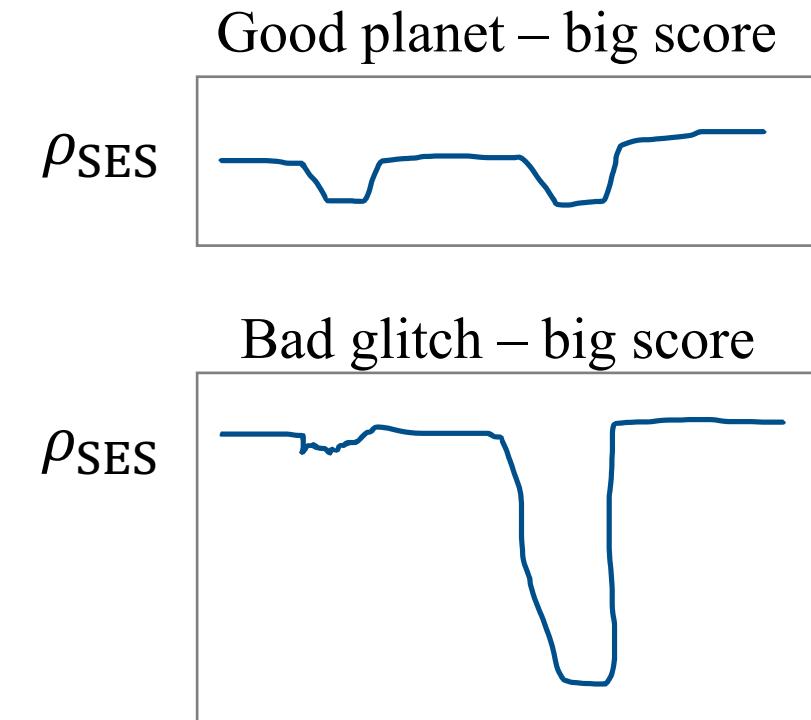


Non-Gaussianity of single-event statistic (SES) distribution

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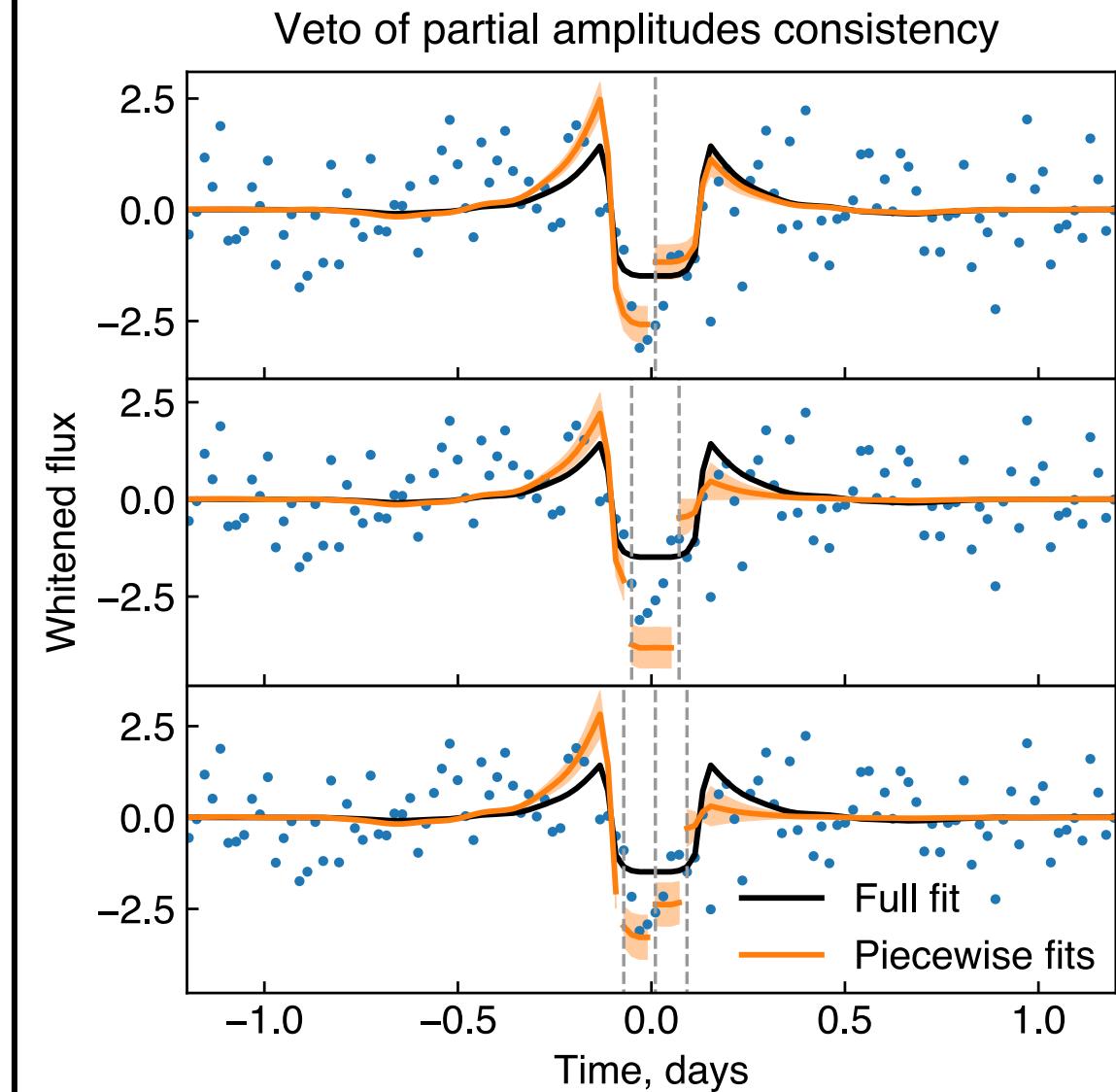
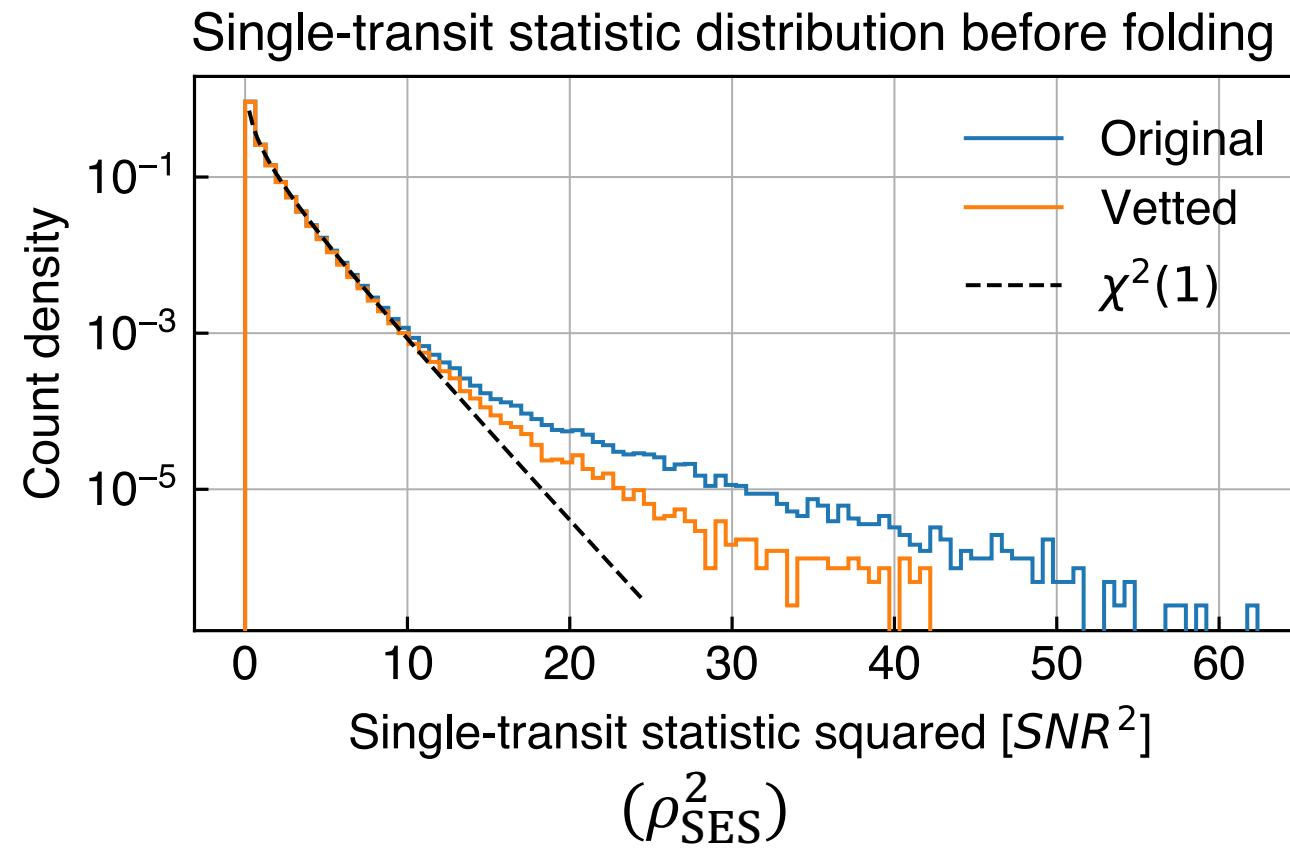
How it contaminates periodic score:



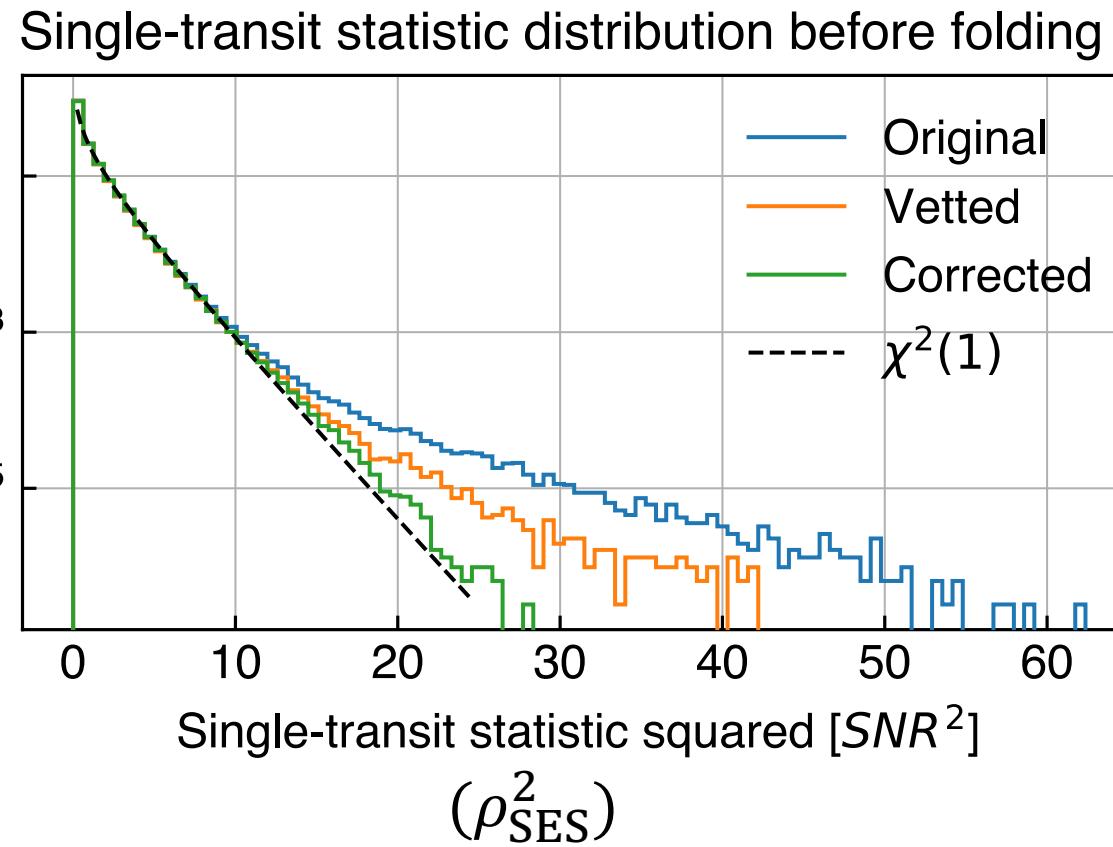
$$\rho_{MES} = \frac{\sum_i \rho_{SES,i}}{\sqrt{\sum_i \text{Var}(\rho_{SES,i})}}$$

Transit shape veto

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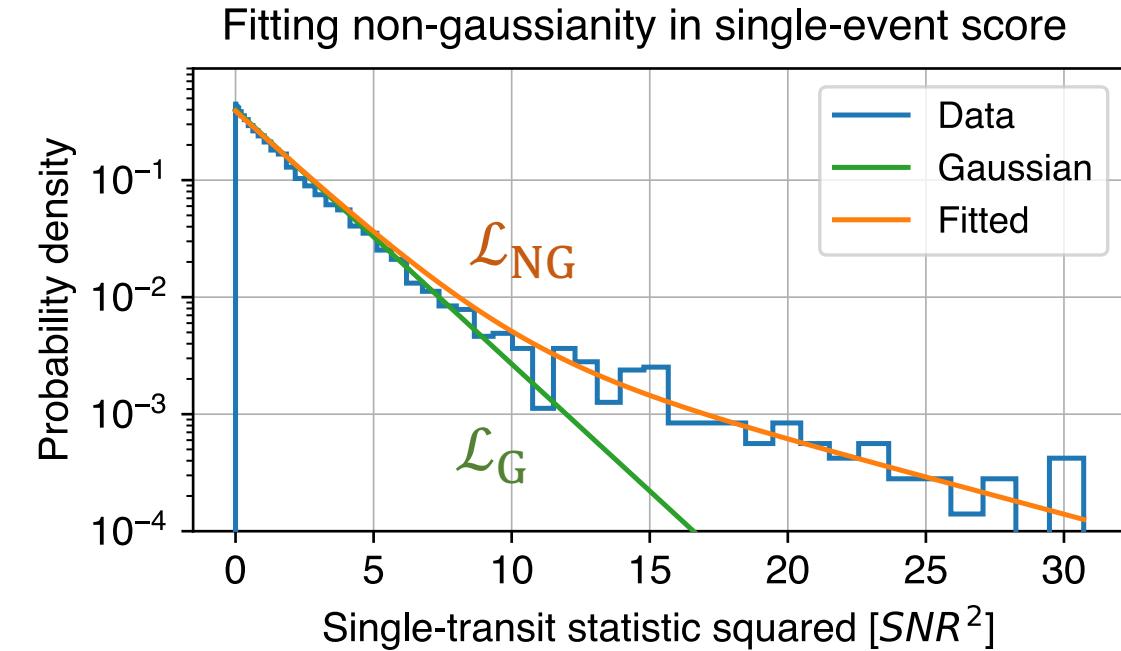


Non-Gaussianity correction



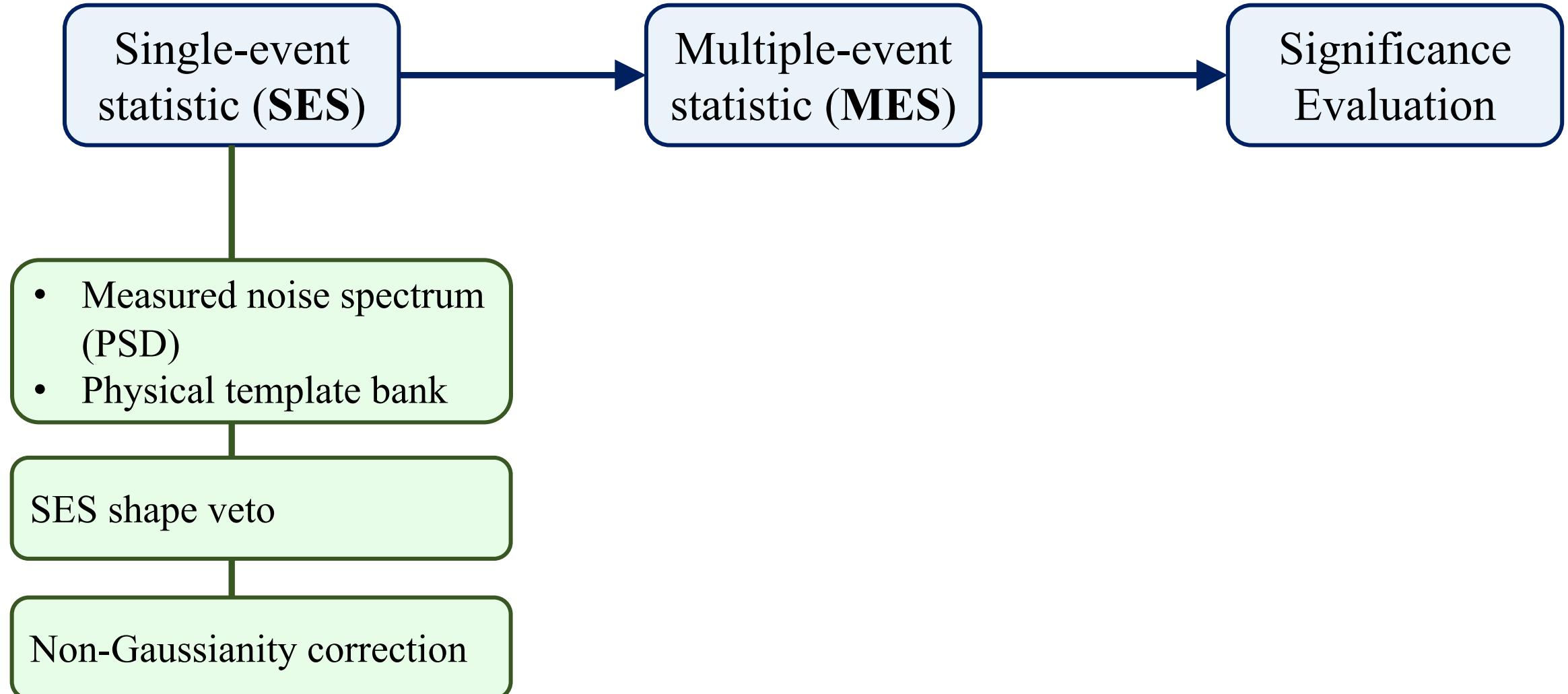
Adding the non-Gaussianity correction to the score:

$$\xi = 2 \log \frac{\mathcal{L}_{NG}(\rho_{SES} | \mathcal{H}_{noise})}{\mathcal{L}_G(\rho_{SES} | \mathcal{H}_{noise})}$$



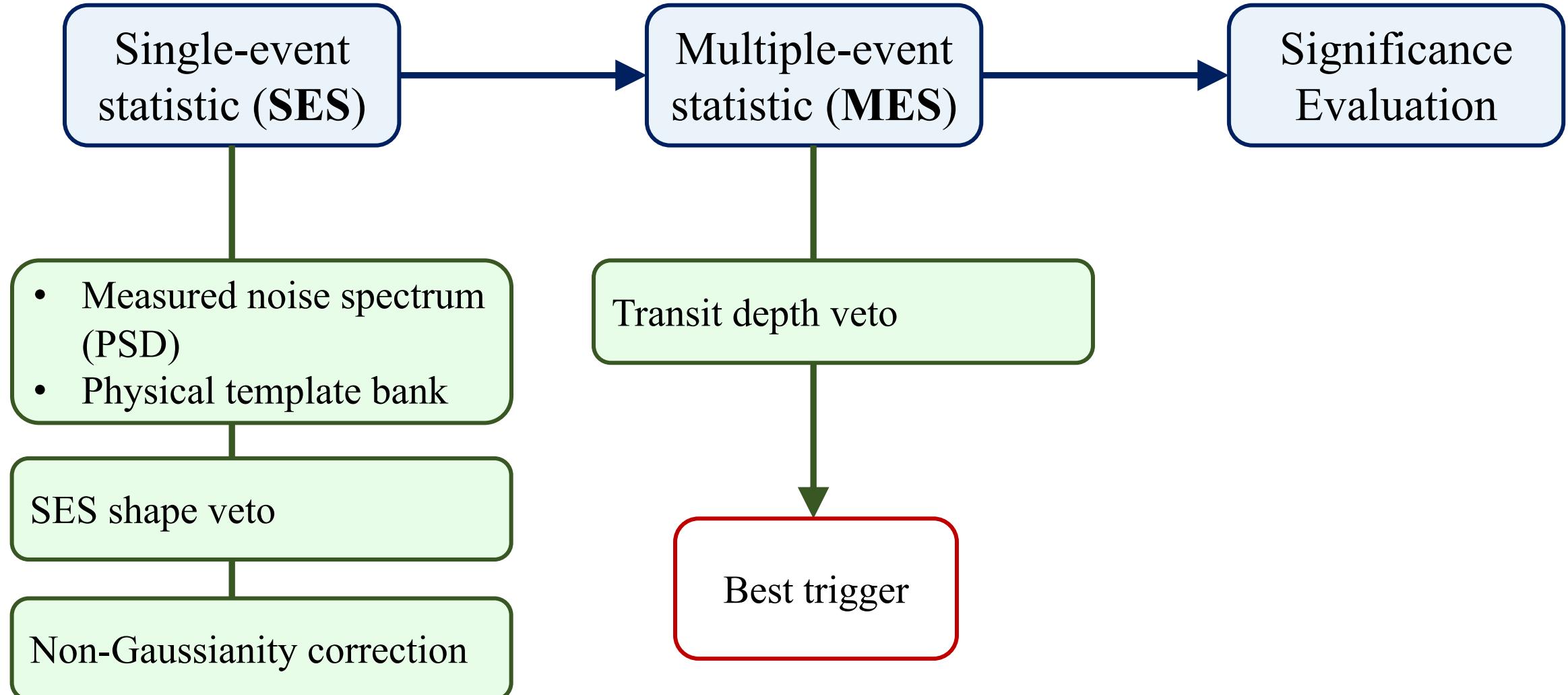
Search scheme

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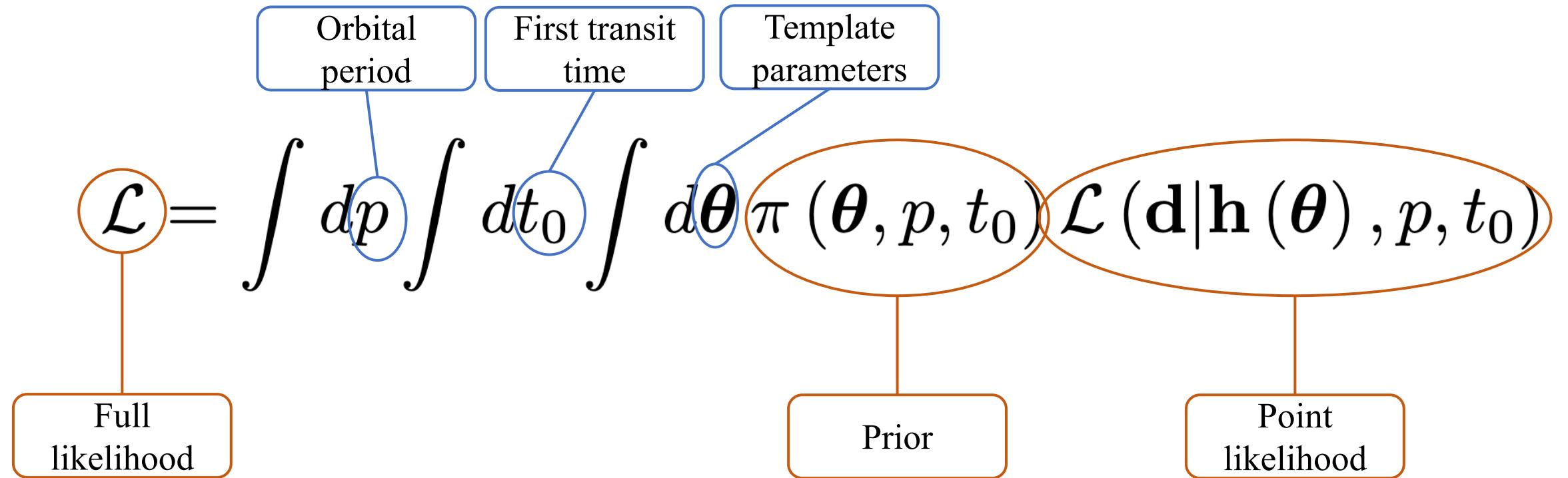


Search scheme

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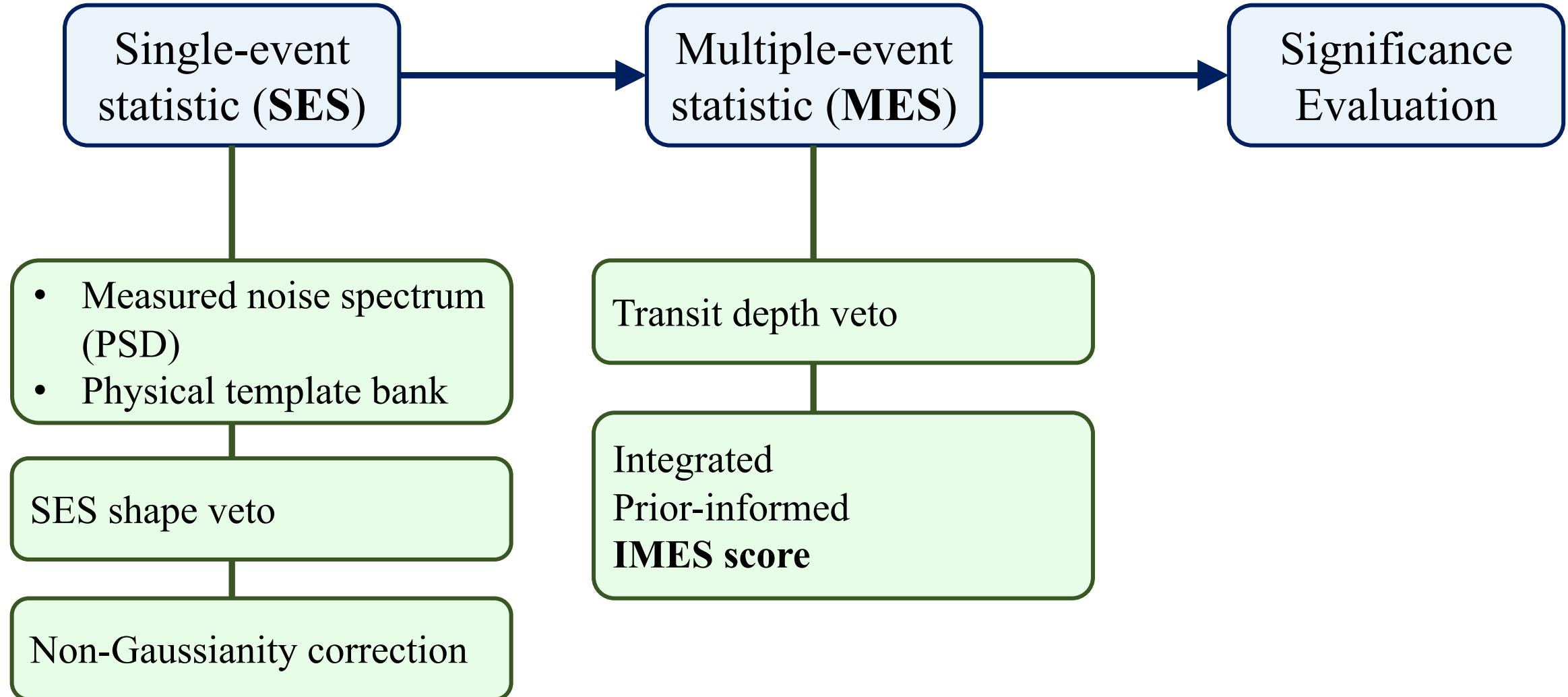
Integral statistic score



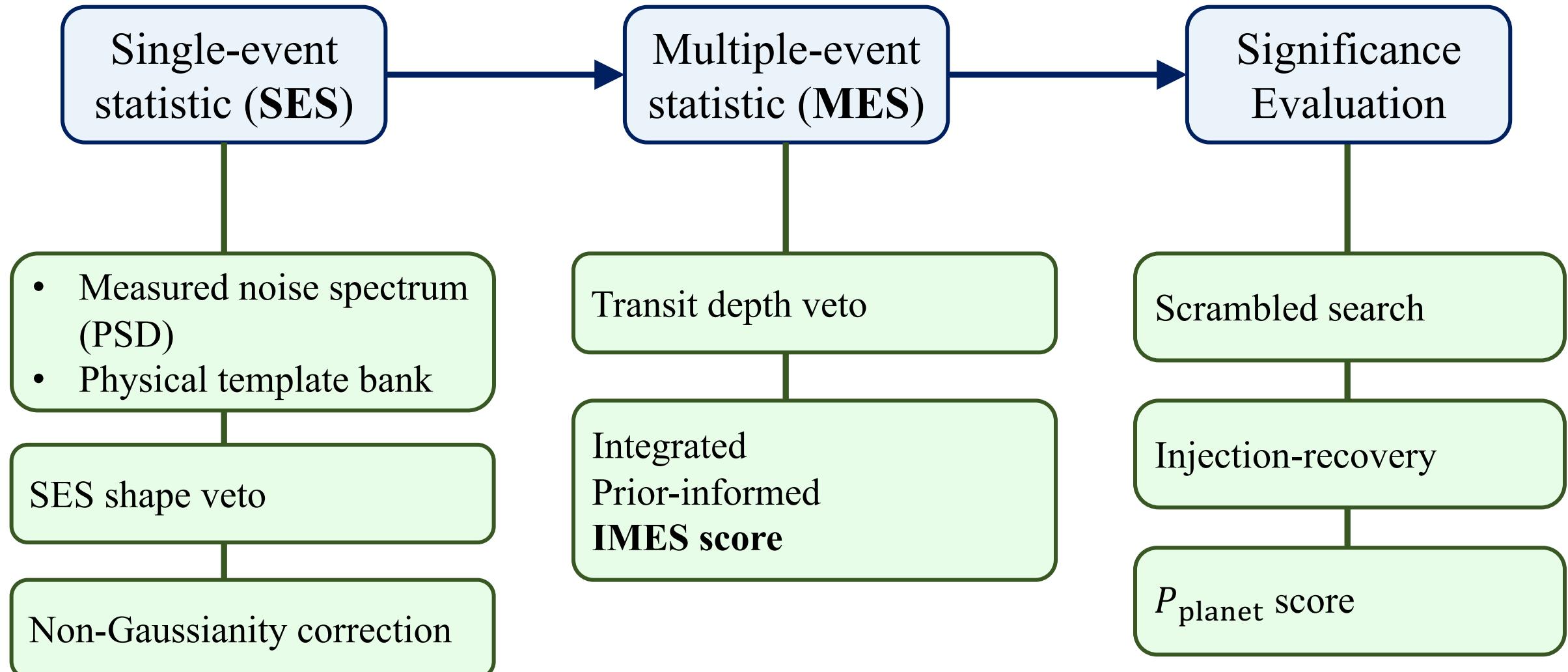
- IMES: Integral multiple-event statistic: $\rho_{\text{IMES}} \propto \log \mathcal{L}$

Search scheme

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Search scheme



P_{planet} significance metric

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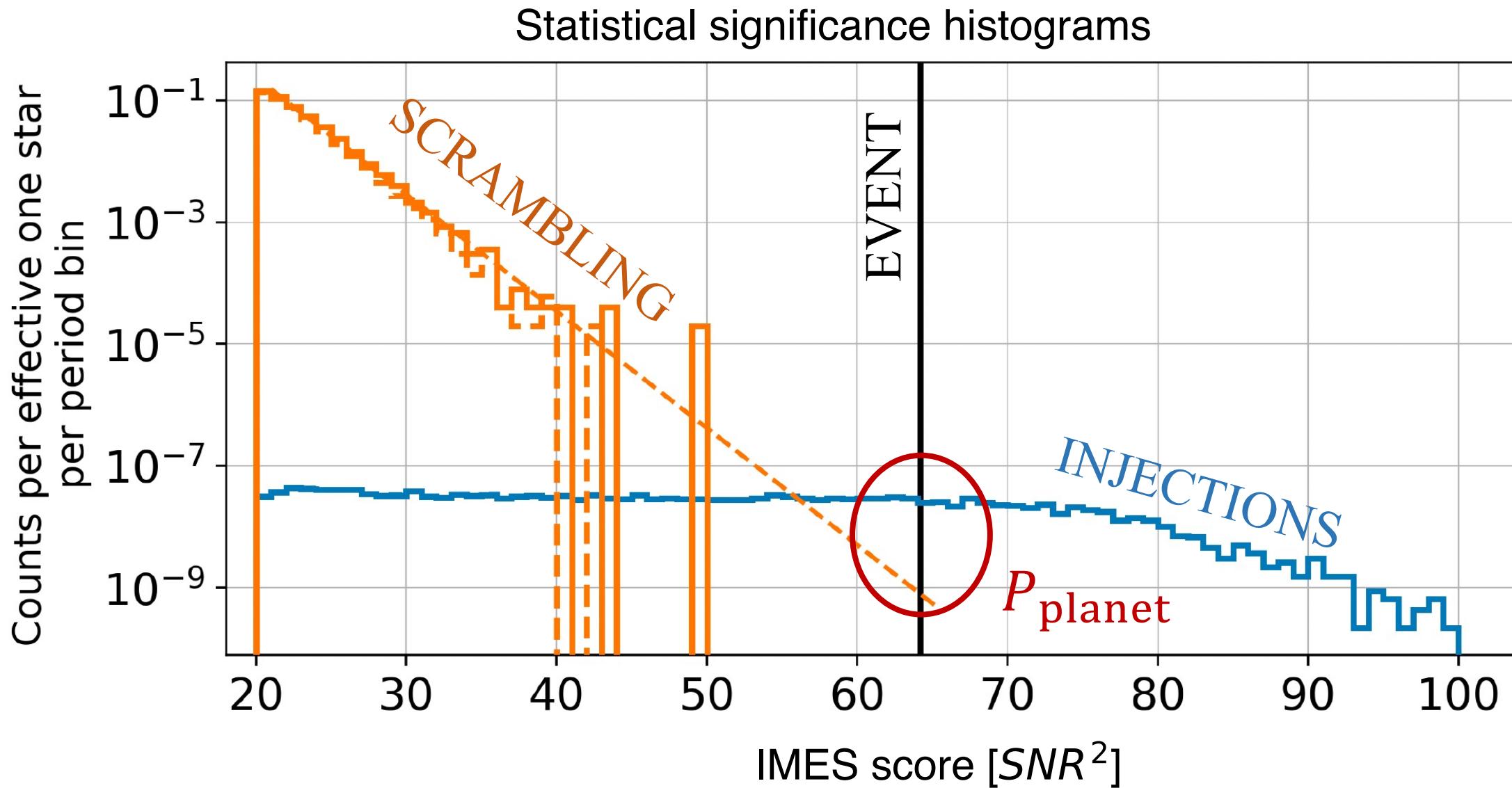
What is the probability that this event is planet and not noise?

$$P_{\text{planet}} = \frac{\pi_p \mathcal{L}(\rho | \mathcal{H}_{\text{planet}})}{\pi_p \mathcal{L}(\rho | \mathcal{H}_{\text{planet}}) + (1 - \pi_p) \mathcal{L}(\rho | \mathcal{H}_{\text{noise}})}$$

The diagram illustrates the components of the P_{planet} formula. A green circle labeled "Prior" points to the term π_p . A blue oval labeled "Planetary distribution" points to the term $\mathcal{L}(\rho | \mathcal{H}_{\text{planet}})$. An orange oval labeled "Background distribution" points to the term $\mathcal{L}(\rho | \mathcal{H}_{\text{noise}})$. The word "INJECTIONS" is written in blue to the right of the planetary distribution oval, and the word "SCRAMBLING" is written in orange to the right of the background distribution oval.

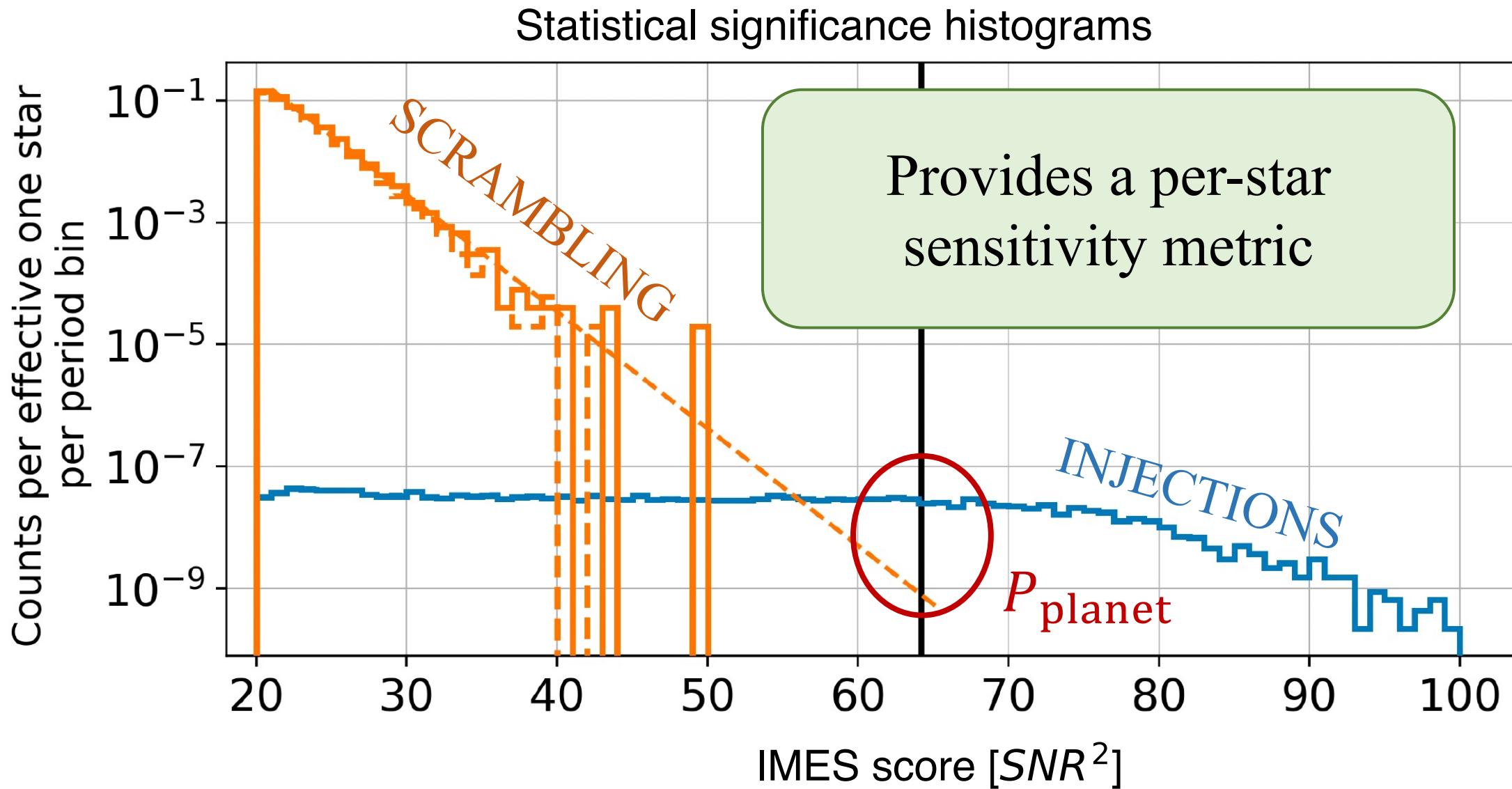
Significance estimation

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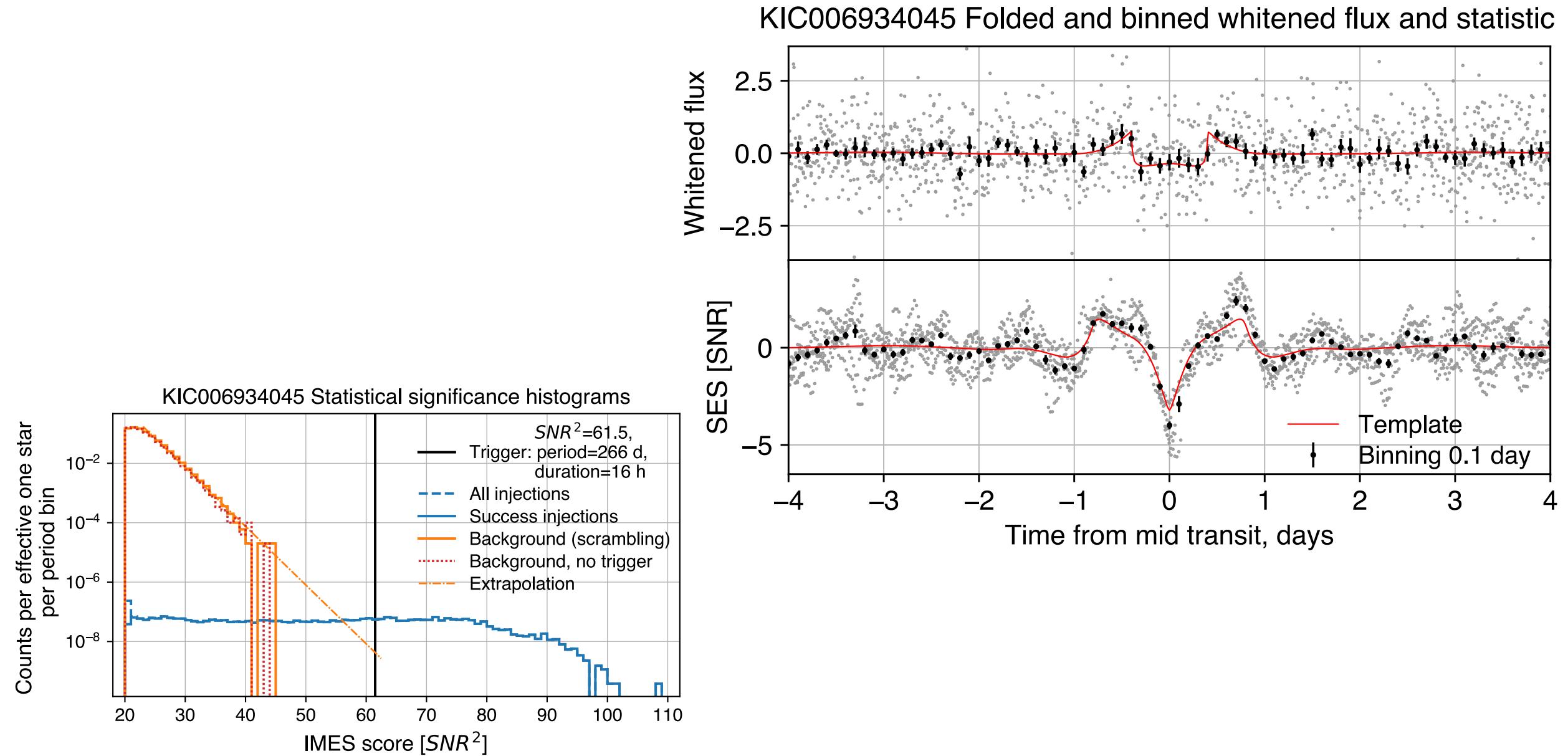


Significance estimation

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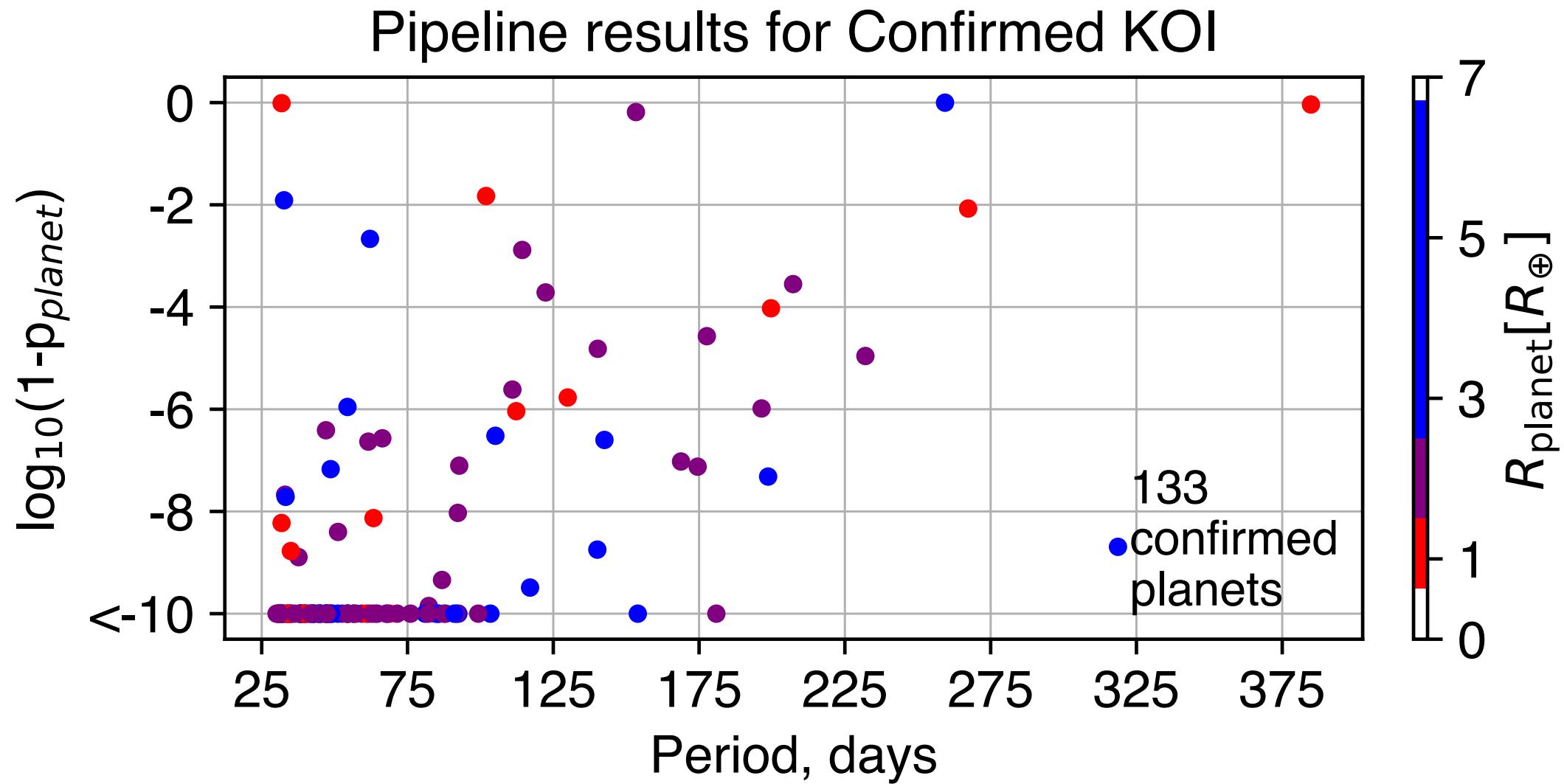
Example of pipeline output



Pipeline performance evaluation

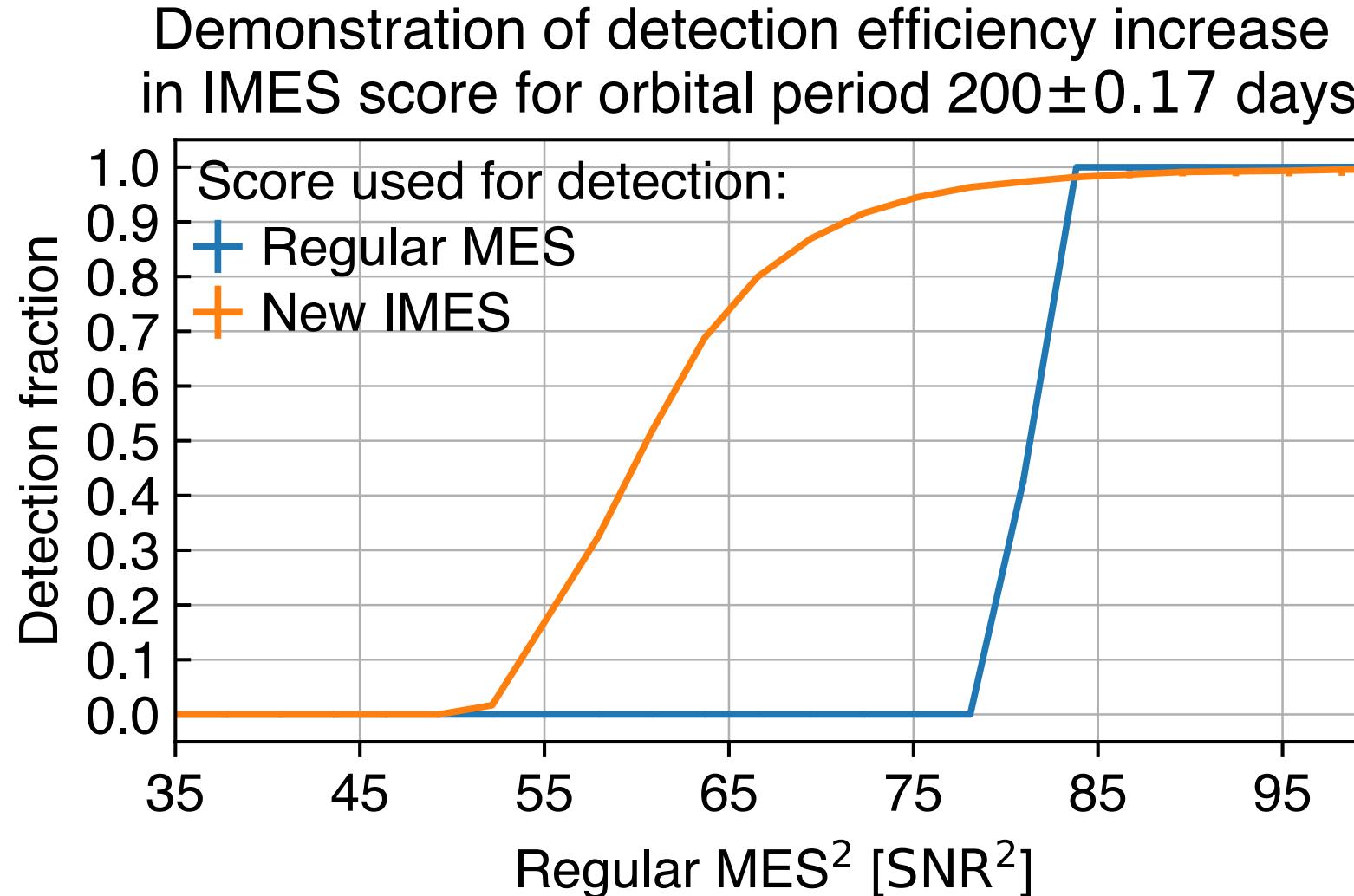
Test 1: recovering faint *Kepler* confirmed planets

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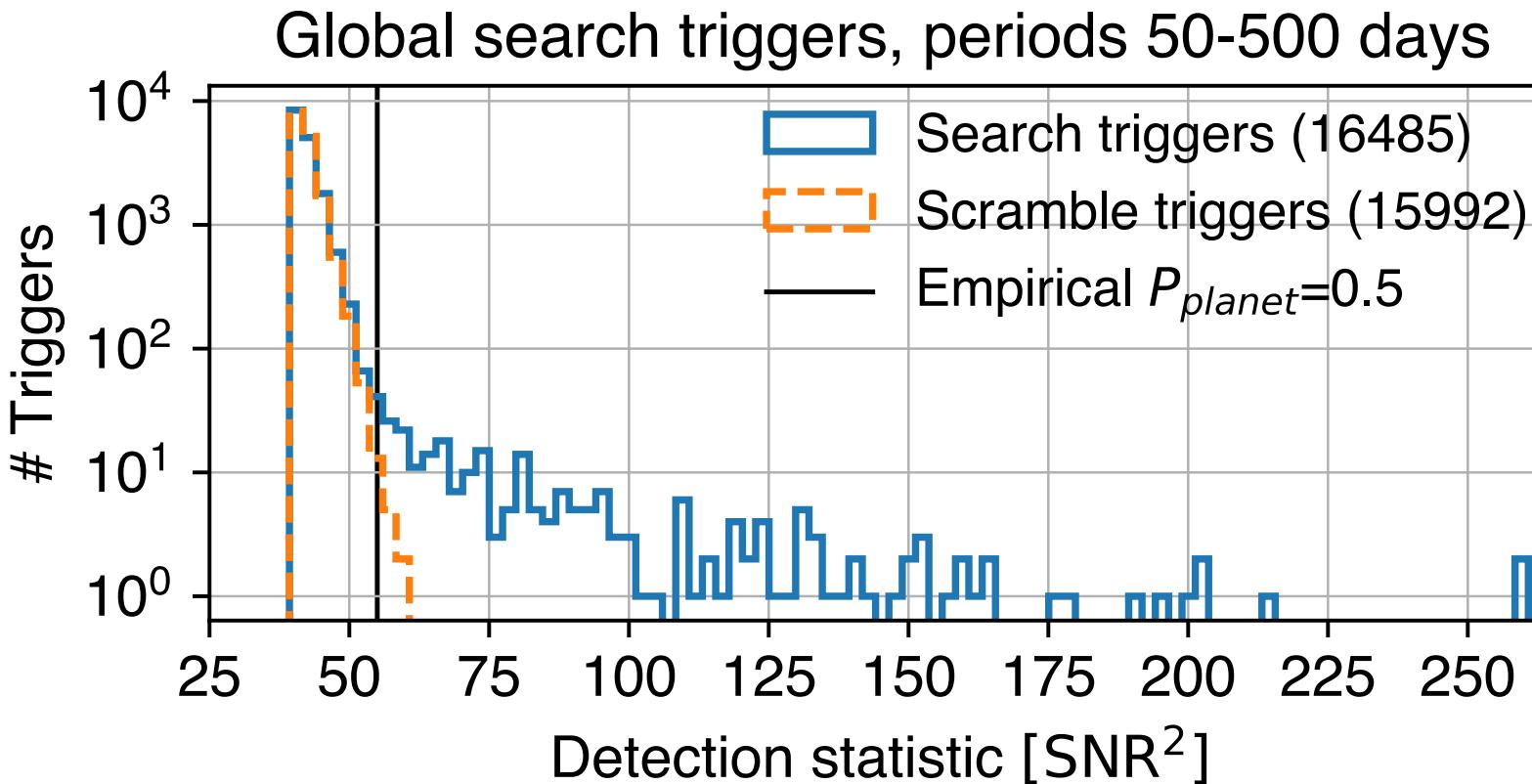
Detection efficiency increase of the new IMES score

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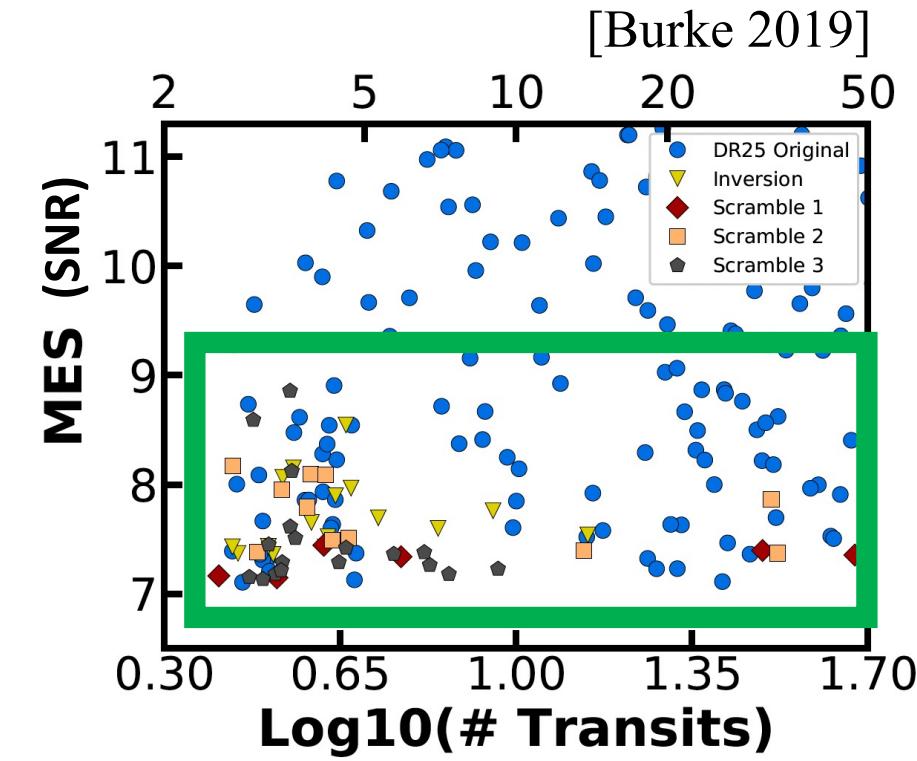
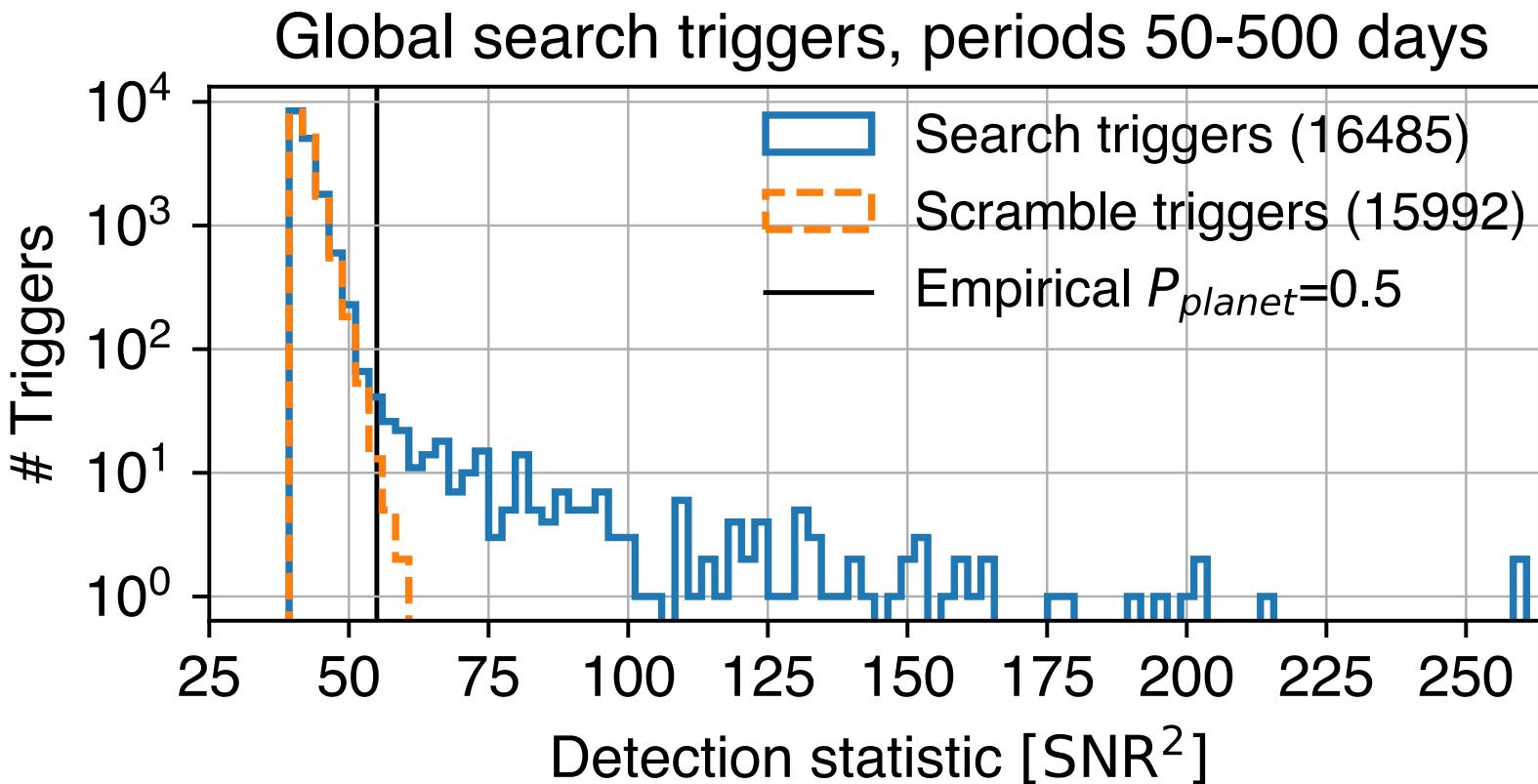
Running the pipeline on the *Kepler* data

Global search trigger distribution



Global search trigger distribution

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Preliminary catalog from the search

